# Topics in Graph Theory

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## About the literature

We will focus on the book Graph Theory written by Benny Sudakov. We study only Chapters 1–7 (Pages 1–45). It has been used as a textbook by several top universities like Swiss Federal Institute of Technology Zurich (ETH), Massachusetts Institute of Technology (MIT).

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### **Recommended Literature:**

- Douglas B. West, Introduction to Graph Theory, Second Edition, 2001.
- Douglas B. West, Introduction to Graph Theory, Solution Manual, 2005.

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# What is a graph?

#### **Definition**

A graph *G* is a pair  $G = (V, E)$  where *V* is a set of vertices and *E* is a (multi)set of unordered pairs of vertices. The elements of *E* are called edges. We write  $V(G)$  for the set of vertices and  $E(G)$  for the set of edges of a graph *G*. Also,  $|G| = |V(G)|$  denotes the number of vertices and  $e(G) = |E(G)|$  denotes the number of edges.

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# Simple graph

### **Definition**

A loop is an edge  $(v, v)$  for some  $v \in V$ . An edge  $e = (u, v)$  is a

multiple edge if it appears multiple times in *E*. A graph is simple if it has no loops or multiple edges.

Unless explicitly stated otherwise, we will only consider simple graphs. General (potentially nonsimple) graphs are also called multigraphs.



## Definition

If  $e = (u, v) \in E(G)$ , then

- *u*,*v* are adjacent (neighbours);
- *e* is incident to *u*,*v*;
- *e* joins *u* and *v*;
- *u* and *v* are the ends of *e*.

Two edges  $e, e'$  are adjacent if  $e \cap e' \neq \emptyset$ .

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# Real world applications

- Let *V* be the set of people in the room, and let *E* be the set of pairs of people who met for the first time today.
- Let *V* be the set of cities in a country, and let the edges in *E* correspond to roads connecting them.

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### Problem (American Mathematical Monthly, 1959)

*Prove that, at any party of six people, we can find three mutual acquaintances (each one knows the other two) or three mutual strangers (each one does not know the other two).*

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# Graph isomorphism

### **Definition**

Let  $G_1 = (V_1, E_1)$  and  $G_2 = (V_2, E_2)$  be graphs. An isomorphism  $\phi: G_1 \to G_2$  is a bijection (a one-to-one correspondence) from  $V_1$  to *V*<sub>2</sub> such that  $(u, v) \in E_1$  if and only if  $(\phi(u), \phi(v)) \in E_2$ . We say  $G_1$  is isomorphic to  $G_2$  if there is an isomorphism between them.



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The function  $\phi: G_1 \to G_2$  given by  $\phi(1) = a$ ,  $\phi(2) = c$ ,  $\phi(3) = b$ ,  $\phi(4) = d$  is an isomorphism.  $\phi(4) = d$  is an isomorphism.

 $R = \{x \in \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^$  $R = \{x \in \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^$  $R = \{x \in \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^$  $R = \{x \in \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^$  $R = \{x \in \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^$  $R = \{x \in \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^$  $R = \{x \in \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^$  $R = \{x \in \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^$  $R = \{x \in \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^$  $R = \{x \in \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^$  $R = \{x \in \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^n : \mathbb{R}^n \times \mathbb{R}^$ 



Isomorphism is an equivalence relation of graphs. This means that

- any graph is isomorphic to itself;
- if  $G_1$  is isomorphic to  $G_2$ , then  $G_2$  is isomorphic to  $G_1$ ;
- <span id="page-11-0"></span>• if  $G_1$  is isomorphic to  $G_2$  and  $G_2$  is isomorphic to  $G_3$ , then  $G_1$ is isomorphic to  $G_3$ .

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# Unlabelled graph

### **Definition**

An unlabelled graph is an isomorphism class of graphs. In the previous example  $G_1$  and  $G_2$  are different labelled graphs but since they are isomorphic they are the same unlabelled graph.

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# The adjacency matrix

Let  $[n] = \{1, \ldots, n\}.$ 

### **Definition**

Let  $G = (V, E)$  be a graph with  $V = [n]$ . The adjacency matrix

 $A = A(G)$  is the  $n \times n$  symmetric matrix defined by

<span id="page-13-0"></span>
$$
a_{ij} = \begin{cases} 1 & \text{if } (i,j) \in E \\ 0 & \text{otherwise.} \end{cases}
$$



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0 otherwise.





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## The incidence matrix

### Definition

Let  $G = (V, E)$  be a graph with  $V = \{v_1, \ldots, v_n\}$  and  $E = \{e_1, \ldots, e_m\}$ .

Then the incidence matrix  $B = B(G)$  of *G* is the  $n \times m$  matrix defined by

$$
b_{ij} = \begin{cases} 1 & \text{if } v_i \in e_j \\ 0 & \text{otherwise.} \end{cases}
$$



1 if v<sup>i</sup> ∈ e<sup>j</sup> ,

 $\overline{\phantom{a}}$ 



 $\sqrt{ }$  $\overline{\phantom{a}}$ 1 1 1 0 0 0 1 1 0 1 0 1 1 0 0 0  $\setminus$  $\begin{matrix} \phantom{-} \end{matrix}$ 

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# **Definition**

<span id="page-17-0"></span>Given  $G = (V, E)$  and a vertex  $v \in V$ , we define the neighbourhood  $N(v)$  of *v* to be the set of neighbours of *v*. Let the degree  $d(v)$  of *v* be  $|N(v)|$ , the number of neighbours of v. A vertex v is isolated if  $d(v) = 0.$ 



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<span id="page-18-0"></span>*Remark. d*(*v*) is the number of 1s in the row corresponding to *v* in the adjacency matrix  $A(G)$  or the incidence matrix  $B(G)$ .





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$$
d(1) = 3, d(2) = 2, d(3) = 2, d(4) = 1, d(5) = 0;
$$
  
5 is isolated.

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#### Fact

*For any graph G on the vertex set* [*n*] *with adjacency and incidence matrices*  $A$  *and*  $B$ *, we have*  $BB<sup>T</sup> = D + A$ *, where* 

$$
D = \begin{pmatrix} d(1) & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & d(n) \end{pmatrix}.
$$

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## Degree notation

### **Definition**

The minimum degree of a graph *G* is denoted  $\delta(G)$ ; the maximum

degree is denoted  $\Delta(G)$ . The average degree is

$$
\overline{d}(G) = \frac{\sum_{v \in G} d(v)}{|V(G)|}
$$

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Note that  $\delta(G) \leq \overline{d}(G) \leq \Delta(G)$ .

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### **Definition**

A graph *G* is *d*-regular if and only if all vertices have degree *d*.

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## **Definition**

A graph *G* is *d*-regular if and only if all vertices have degree *d*.

Is there a 3-regular graph on 9 vertices?

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## Handshaking lemma

## Theorem (Degree sum formula)

*For every*  $G = (V, E), \sum_{v \in G} d(v) = 2|E|$ .

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## Proof.

In the sum  $\sum_{v \in G} d(v)$ , every edge  $e = (u, v)$  is counted twice: once from *u* and once from *v*.

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## Corollary (Handshaking lemma)

*Every graph has an even number of vertices of odd degree.*

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# *Thank you!*

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